# Development of personal integrated sterilization machine for new normal phase preparation of the 2019-nCoV outbreak

by Retno Sari Mahanani

**Submission date:** 06-Apr-2022 09:11PM (UTC+0700)

**Submission ID:** 1803382430

File name: Hariono\_2021\_IOP\_Conf.\_Ser.\_\_Earth\_Environ.\_Sci.\_672\_012089.docx (696.88K)

Word count: 2363
Character count: 11944

### PAPER • OPEN ACCESS

Pevelopment of personal integrated sterilization machine for new normal phase preparation of the 2019-nCoV outbreak

14 To cite this article: B Hariono *et al* 2021 *IOP Conf. Ser.: Earth Environ. Sci.* **672** 012089



9 View the <u>article online</u> for updates and enhancements.

### You may also like

- Silver nanoparticles: synthesis, properties, 15 ology, applications and perspectives Quang Huy Tran, Van Quy Nguyen and Anh-Tuan Le
- Review on water quality sensors Peter Kruse
- 11 matic Spray Desinfectant Chicken With Android Based On Arduino Uno Akhmad Ahfas, Mohammad Bahrul Ulum, Dwi Hadidjaja Rasjid Saputra et al.



## Development of personal integrated sterilization machine for new normal phase preparation of the 2019- nCoV outbreak

### B Hariono<sup>1</sup>, R S Mahanani<sup>2</sup>, S Nusantoro<sup>3</sup> and S Kautsar\*<sup>4</sup>

Department of Agricultural Technology, Politeknik Negeri Jember, Jl. Mastrip PO Box 164 Jember - East Java, Indonesia

<sup>2</sup>Department of Agribusiness, Politeknik Negeri Jember, Jl. Mastrip PO Box 164 Jember - East Java, Indonesia

<sup>3</sup>Department of Animal Husbandry, Politeknik Negeri Jember, Jl. Mastrip PO Box 164 Jember - East Java, Indonesia

<sup>4</sup>Department of Engineering, Politeknik Negeri Jember, Jl. Mastrip PO Box 164 Jember - East Java, Indonesia

Abstract. The disease outbreak caused by the 2019-nCoV virus is growing so rapidly that the WHO has categorized this outbreak as a pandemic. In Indonesia, as of March 24, 2020, there were 686 patients who tested positive for the 2019-nCoV virus with 55 deaths. This has made the government extend the disaster period of the Coronavirus outbreak until the end of May 2020. Various efforts have been made by the Indonesian government, such as: opening emergency hospitals, implementing social distancing, and preventing viruses by spraying massive disinfectants. Disinfectant spraying is carried out using the help of a fire engine or using a spray device. Spraying of disinfectant is carried out on public roads and public spaces. Indonesia is starting to prepare for the new normal phase in the midst of the coronavirus pandemic which continues to infect millions of people in the world. The government has instructed that the phase of normality can be well prepared. For the readiness of the new normal corona, 13 Ministry of Health and the Task Force for the Acceleration of Handling Covid-19 have compiled health protocols such as washing hands, maintaining distance, coughing, and sneezing ethics, and wearing masks. Based on the problem, an integrated sterilizer machine was developed. It can be used for workers during the New Normal phase. The machine is equipped with an automatic handwashing device, an automatic temperature gauge, and a UV booth for sterilizing goods carried by workers at Politeknik Negeri Jember.

### 1. Introduction

Decc ber 2019 saw an outbreak of pneumonia of a previously unknown eti by gy in Wuhan, China. A new coronavirus was identified as the virus that cases it, which was later named 2019-nCoV by the World Health Organization (WHO). January 25, 2020, a total of 1975 cases have beet confirmed nationally with another 2684 cases suspected to be caused by 2019-nCoV I Covid-19 [9]. On January 31, the first 2 cases of a novel coronavirus in the UK, [10] the first 2 cases in Russia, [11], and the first cases in Sweden and in Spain were reported. Canada reports the 4th case. The case in Indonesia itself was first discovered on March 1, 2020, while currently, the cases found in Indonesia has reached 893 [12]. Looking at the cases that have emerged, WHO equates preventionIsuppression of the number of

<sup>\*</sup>E-mail: syamsiar\_kautsar@polije.ac.id

10

sufferers with Middle-East Respiratory Syndrome (MERS) and Severe Acute Respiratory Syndrome (SARS), human-to-human transmission occurs through droplets, contact, and fomites (sources of infection from inanimate objects) [1].

Fomites or sources of inanimate object transmission are one of the 2019-nCoV transmission media, so this research aims to present a solution in the form of using robots for sterilization. The hope of this research is to ensure that the environment does not fall into the Fomites category. Research on the use of robots to deal with hazardous environments was carried out, among others, by [2] [3] [4] [5] [6]. While the type of robot used in this research is a type of robot with a differentiated drive, such as research conducted by [7] [8]. It's just that the front of the robot uses Omni wheels so that maneuvers can be done more flexibly.

The developed robot can be operated manually using a joystick. The robot is connected to the operator's PC (Ground Station) using a 900MHz telemetry module. The robot is also equipped with an FPV Camera so that room images can also be accessed on the PC screen at the Ground Station. Based on the odometry system with a rotary encoder sensor mounted on the bottom of the robot, the robot can also be operated semi-automatically to perform sterilization evenly and sequentially in the room. So it is hoped that the sterilization process will be even and comprehensive, in the end, the spread through the 2019-nCoV fomites can be suppressed.

### 2. Related Work

The development of technology in the field of electronic instrumentation continues to be developed to help humans visualize existing analog quantities into digital quantities. One of the developments in electronic instrumentation is to use a control system to provide supervision to a system [9]. The convenience of this control system is widely used in the health sector, research laboratories, and also for industry, especially the food industry, which prioritizes the hygiene of production machines and cleaning equipment. Currently, to prevent the equipment contaminated with bacteria, the tool is stored in the UV box so that its hygiene is maintained, but if the UV lamp is off, it cannot be known quickly because the UV box is light-tight or not transparent, while the on-off UV lamp greatly affects the hygiene of the tool and results in the product will be contaminated with bacteria. When the UV lamp is turned off, it is certain that microbes will quickly grow in sterilized equipment, this is very dangerous. One of the studies that made use of UV lamps was a study conducted by Arisanti (2004)[10], namely, The Effectiveness of Sterilization Using Ultraviolet (UV) Light on Decreasing the Number of Air Germs in the IBS Operating Room at the Tugurejo Hospital Semarang. Several sterilization boxes have been sold commercially in the market, but the light-tight sterilization boxes that are widely needed in the industry are not equipped with a control system at a relatively expensive price. [11]

### 3. System Design

### 3.1. Hardware Design

The device is designed in the form of a cupboard with a length of 160cm and a height of 80cm to wash hands. 2 automatic taps are installed in the hand washing area, each of which functions to pump water and soap. The automatic faucet works using a proximity sensor so that the user can just bring his hand closer to activate the pump. There is a water level sensor that is used to detect the water capacity in the reservoir. On the right side of the sink, a box measuring 80cm x 80cm x 80cm is made. The design of the handwashing device is shown in Figure 1.

In the box installed 3 units of 9 watt UV lamps. The use of UV lamps is used to sterilize items such as bags, cellphones, helmets, etc. UV sterilizer box door is equipped with a proximity sensor to open the door connected to a servo motor. The entire operation of the handwashing device is touchless. This aims to reduce the risk of exposure to viruses from droplet contact. All sensors and actuators are connected to the ATMega328 microcontroller. For the power supply of the handwashing device, it uses PLN 220VAC electricity. Figure 2 is an illustration of the system block diagram used in the tool.

IOP Conf. Series: Earth and Environmental Science 672 (2021) 012089

doi:10.1088/1755-1315/672/1/012089

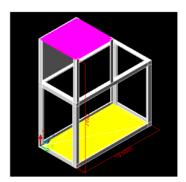


Figure 1. Hardware design

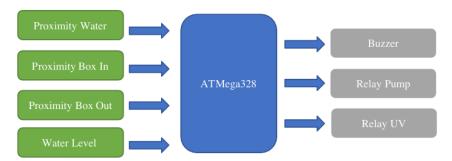


Figure 2. Diagram block system

### 3.2. 3.2 Software Design

The device is designed using 1 controller. The controller uses an ATMega328 chip programmed using the Arduino programming language. If the proximity sensor on the water pump is blocked, the water pump will be active so that clean water will come out. Conversely, if the proximity sensor on the soap dispenser is blocked, the soap pump will be active. If the proximity sensor on the door side of the sterilization box detects an obstacle, the servo motor will activate so that the door opens. Next, the controller will wait for the object to be put into the UV sterilizer box. If the sensor inside the box detects an object, the door will close automatically. The controller will activate the UV lamp in a few seconds.

After the object is sterilized using a UV lamp, the door will open. In this position, objects can be removed by the user. After the sensor detects that the object has been taken, the door will close again. The pump motor and the UV sterilizer work partially, so the user can use one or both of the features alternately. Figure 3 is a system block diagram of the device is made.

doi:10.1088/1755-1315/672/1/012089

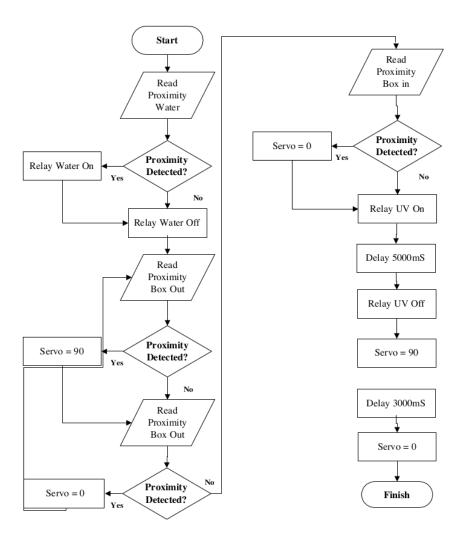


Figure 3. Flowchart System

### 4. Result and Discussion

### 4.1. System Realization

The work of the tool is shown in Figure 4. The frame for the device is made using iron and a combination of plywood covered with paper. The sensor placement configuration looks like the description in Figure 4. A water storage reservoir is placed on the inside of the table. The buzzer will sound when the water level is about to run out. The device is also equipped with a drain tank, so that the tool can be used

portable in various locations. The pin mapping used on the ATMega328 microcontroller chip is shown in table 1. The whole system uses only one controller.



Figure 4. Sterilization Unit

Table 1. Pin Mapping

ATMega328 Pin	Sensor	
2	Proximity water	
3	Proximity Box Out	
4	Proximity Box In	
5	Water Level Sensor	
6	Relay UV	
7	Relay Water Pump	
8	Servo	
13	Buzzer	

### 4.2. Testing result

Testing is done by experimenting with the work functions of various features on the device. Figure 5 is a test of the work function of soap. Figure 7 is a test function of the water level sensor. If the water level sensor detects that the water is running out, the water and soap pump motor will not work.

doi:10.1088/1755-1315/672/1/012089







Figure 5. Water Pump test

Figure 6 Soap pump test

Figure 7 Water level test

Furthermore, the UV sterilization box function test was performed. Figure 8 is the position when the door opens automatically. Red mark is the position where the object is placed. Figure 9 is the box condition when the UV lamp is on. From the whole testing process, the system has worked well.





Figure 8 Door open automatically

Figure 9 UV lamp on

### 5. Conclusion

The development of the Covid-19 pandemic has slowed things down. The imposition of social restrictions means that some activities cannot be carried out directly. The Ministry of Health has also implemented a health protocol for intense hand washing. In this study, a lardwashing and UV sterilizer device was created which worked well. This device can be used to help reduce the risk of exposure to the Covid-19 virus.



doi:10.1088/1755-1315/672/1/012089



### 6. Acknowledgment

The authors would like to acknowledge the financial support of this work by grants from PNBP, State Polytechnic of Jember. The author also thanked the P3M and Information Technology Department, State Polytechnic of Jember, which has provided support and assistance in completing this research.

### References

- [1] WHO 2019 Novel Coronavirus(2019-nCoV) Situation Report 22 World Heal. Organ.
- [2] Muthiah M, Nirmal K and Sathiendran R 2015 Low cost radio frequency controlled robot for environmental cleaning 2015 International Conference on Circuits, Power and Computing Technologies [ICCPCT-2015] (IEEE) pp 1-5.
- [3] Carpentiero M, Gugliermetti L, Sabatini M and Palmerini G B 2017 A swarm of wheeled and aerial robots for environmental monitoring 2017 IEEE 14th International Conference on Networking, Sensing and Control (ICNSC) (IEEE) pp 90-5
- [4] Haque Usmani M R, Maruf Rahman L, Ahmed S, Chowdhury I and Uddin J 2019 Hazard Reconnaissance Rover Using Raspberry Pi and Multiple Sensors 2019 International Conference on Robotics, Electrical and Signal Processing Techniques (ICREST) (IEEE) pp 192-5.
- [5] Guo H, Song L, Liu J, Wang F-Y, Cao D, Chen H, Lv C and Luk P C-K 2018 Hazard-evaluationoriented moving horizon parallel steering control for driver-automation collaboration during automated driving *IEEEICAA J. Autom. Sin.* 5 1062-73
- [6] Kim Y-D, Jung S-H, Gu D-Y, Kim H-K and Song C-H 2017 IoT Sensor Based Mobility Performance Test-Bed for Disaster Response Robots 2017 6th IIAI International Congress on Advanced Applied Informatics (IIAI-AAI) (IEEE) pp 990-1
- [7] Aranda J, Grau A and Climent J Control architecture for a three-wheeled roller robot AMC'98 -Coimbra. 1998 5th International Workshop on Advanced Motion Control. Proceedings (Cat. No.98TH8354) (IEEE) pp 518-23
- [8] Cuong T C, Dinh Tu N, Dang L H, Bao T Q and Ngon N C 2017 An application of movement direction control for the three wheeled mobile robots using visual information 2017 Seventh International Conference on Information Science and Technology (ICIST) (IEEE) pp 121-8
- [9] Wang W, Tang J and Wei F 2020 Updated understanding of the outbreak of 2019 novel coronavirus (2019-nCoV) in Wuhan, China J. Med. Virol. 92 441-7
- [10] Department of Health and Social Care 2020 CMO confirms cases of coronavirus in England gov.uk
- [11] TASS 2020 First two persons infected with coronavirus identified in Russia Russ. News Agency
- [12] BNPB 2020 Situasi Virus Corona (COVID-19) 27 Maret 2020 Satuan Tugas Penanganan COVID-19
- [13] Putov V V, Putov A V, Ignatiev K V, Belgradskaya E V and Kopichev M M 2015 Autonomous three-wheeled robot with computer vision system 2015 IEEE NW Russia Young Researchers in Electrical and Electronic Engineering Conference (EIConRusNW) (IEEE) pp 262-5

# Development of personal integrated sterilization machine for new normal phase preparation of the 2019-nCoV outbreak

Hevv	/ Hormai p	mase preparatio	11 01 1116 2019-1	icov outbre	tak
ORIGINA	ALITY REPORT				
2 SIMILA	3% ARITY INDEX	21% INTERNET SOURCES	19% PUBLICATIONS	14% STUDENT PA	PERS
PRIMAR	Y SOURCES				
1	Submitt Student Pape	ed to Reykjavík	University		3%
2	Gamero bakery	uitral, Marcela S -Vega, Paula Jim and farinaceous tional Journal of , 2021	nénez. "Seawe foods: A mini	eds in -review",	3%
3	earchive Internet Sour	•			2%
4	"Update 2019 no	lang, Jianming Ted understanding vel coronavirus China", Journal	g of the outbr (2019 - nCoV)	eak of in	2%
5	publikas Internet Sour	si.polije.ac.id			2%
		• 1 • 1			_

7	www.longdom.org Internet Source	1 %
8	daten-quadrat.de Internet Source	1 %
9	Ippm.ibrahimy.ac.id Internet Source	1 %
10	storage.googleapis.com Internet Source	1 %
11	D A Svetlov, E D Svetlova, D D Svetlov, T S Egorova et al. "Research into Antibacterial Activity of Novel Disinfectants Derived from Polyhexamethylene Guanidine Hydrochloride", IOP Conference Series: Materials Science and Engineering, 2021	1 %
12	mafiadoc.com Internet Source	1 %
13	theicph.com Internet Source	1 %
14	eprints.poltekkesjogja.ac.id Internet Source	1 %
15	iopscience.iop.org Internet Source	<1%
16	www.aquaticwhirlpools.com Internet Source	<1%



Akshay Kumar Chaudhry, Payal Sachdeva. "Coronavirus Disease 2019 (COVID-19): a new challenge in untreated wastewater", Canadian Journal of Civil Engineering, 2020

<1%

Publication

18

www.journaljpri.com

Internet Source

<1%

Exclude quotes

Off

Exclude matches

Off

Exclude bibliography Or